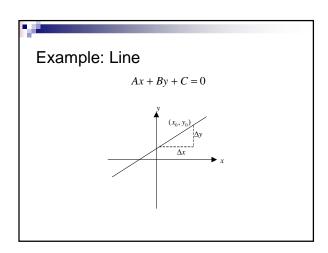
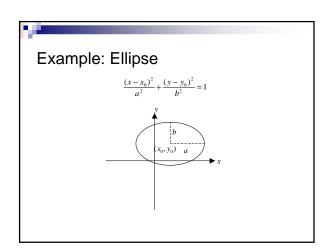


# 2D Geometric Objects

- A 2D geometric object is a set of points in the plane
- Almost always an infinite set of points

  □ Therefore, can't simply list all of those points
- Usually, equation used to represent object, defining relation between x and y coordinates





### Parametric Equations

- For some geometric objects, it's more convenient to use parametric representation
- For lines, easy enough to find coordinates of points on line: y = m x + b
- For more intricate curves, not so easy
- Need to solve equation for y in terms of x
- More complicated for 3D and higher dimensional spaces
- Use parametric equations instead

# Parametric Equation

Introduce an independent variable t

$$x = f(t)$$

$$y = g(t)$$

Parametric equation of a line

Parametric equation of an ellipse

$$x = x_0 + at$$

$$x = x_0 + a\cos t$$

$$y = y_0 + bt$$

$$y = y_0 + b \sin t$$

# Space

- A space is a collection of all points or coordinates
- Types of space in a graphics system:
  - □ Object Space
  - □ World Space
  - □ Device Space
- Each space has own coordinate system
- Objects can be mapped between coordinate systems through transformations

# Types of Coordinate Space

- Object Coordinate System
  - □ Local or modeling coordinate system
  - ☐ Typically choose a convenient coordinate system for the individual object
    - E.g., Center an ellipse at (0,0)
  - □ Object later placed in world space through transformations (e.g., translations, scaling, etc)



# Types of Coordinate Space

- World Coordinate System
  - □ Common reference space for all objects in model
  - □ Shared virtual world for modeling and rendering subsystems
  - $\Box$  Object transformations used to place objects in world space  $$^{y}_{\uparrow}$$



# An object in world space

# Types of Coordinate Space

- Device Coordinate System
  - ☐ Display of an output device (e.g., screen or printer)

