Chapter 12

(Sec. 12.1 - 12.4)

Concurrency – Synchronization with Semaphores and Monitors

Thread/Process

Thread - A program unit that can execute concurrently with other program units. *Heavyweight process* - Has its own address

space Lightweight processes - Processes that share an

address space

Task - A well-defined unit of work performed by some thread

*** No consistent definition for these terms ***

Concurrency Issues

Communication

How a thread obtains information produced by another thread $% \left({{{\bf{n}}_{{\rm{p}}}} \right)$

- Shared memory
- Message passing

Synchronization

- Controlling the relative order that operations occur in different threads $% \label{eq:controlling}$
- Busy-waiting (spinning)
- Blocking (scheduler-based)

Thread Creation

- Control flow Co-begin Parallel loops Subprograms
 - Launch-at-elaboration Fork Implicit receipt Early reply





C#

```
Parallel.For(0, 3, i => {
    Console.WriteLine("Thread " + i + " here");
});
```

High Performance Fortran (HPF)

forall (i=1:n-1) A(i) = B(i) + C(i) A(i+1) = A(i) + A(i+1)end forall

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Launch-at-Elaboration

Ada tasks are created and begin execution when the enclosing program unit starts

The program unit doesn't terminate until all enclosed tasks terminate

Each task has a single point of control

Ada Task Example

with text_io; use text_io;

procedure ConcurrentWriter is

task WriteA; task body WriteA is begin for j in 1..10 loop put('A'); new_line; end loop; end WriteA; task WriteB; task body WriteB is begin for j in 1..10 loop put('B'); new_line; end loop; end WriteB:

end ConcurrentWriter;

begin

null;

Subprogram Concurrency

Tasks differ from ordinary subprograms in that:

- 1. A task may be implicitly started
- 2. When a program unit starts the execution of a task, it is not necessarily suspended
- 3. When a task's execution is completed, control may not return to the caller

Tasks usually work together

fork in C

- fork function is executed in a parent process and creates a child process
 Children share their parent's code
- Child process begins executing immediately after being created; and parent resumes
- The fork function returns the child's process ID number to the parent and returns 0 to the child
- Processes are killed at the end of their code
- A wait function can be called to suspend a parent until a child terminates

fork in C int childNum = fork();

```
if (childNum == 0)
    // child process code
else {
    // parent process code
}
```

fork Example I got %d as pidl\n", pid); sleep(4); } else { /* pid > 0 in the parent process */ printf("I"m the parent process. wait(&status); // Wait for child to terminate printf("Child done. status = %d\n", status); } }

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Synchronization Mechanism that controls the order in which tasks execute Required when a task must wait for some other task to complete an activity before it can continue Task communication is necessary for synchronization

Involves exchange of control info

Interaction Between Tasks

Communication

Sharing and exchanging information between tasks

- 1. Parameters
- 2. Shared non-local variables (shared memory model must guarantee *mutually exclusive* access)
- 3. Message Passing (distributed processing model)

Interaction Between Tasks

 $\ensuremath{\textit{Synchronization}}$ - mechanism that controls the order in which processes execute

- Competition each process requires exclusive use of a resource
- Cooperation two processes work on parts of the same problem

Implementing Synchronization

Make some operation atomic

• Mutual exclusion - only one thread is executing a *critical section* at any given point in time

Methods for Providing Synchronization

- Semaphores
- Monitors
- Message Passing

Semaphores

Introduced by Edsger Dijkstra in 1965 A data structure consisting of An integer counter A queue of suspended tasks There are two *atomic* (indivisible) operations wait release (originally called *P* and *V* - see Fig. 12-14 for detained implementation)

Can be used to provide both cooperation and competition synchronization

Semaphore - WAIT

procedure wait(sem)

if sem.counter > 0 then
 sem.counter--

else

put the calling task in **sem.queue** transfer control to a task from ready-list // Deadlock if none are ready

end

Semaphore - RELEASE

procedure release(sem)

if sem.queue.is_empty() then
 sem.counter++

else

put calling task in ready-list transfer control to a task from sem.queue end

Shared Data and Semaphores Critical Section - a portion of code that must

be treated as an atomic unit Access to shared data occurs in a critical section that is guarded by a semaphore



Shared Data and Semaphores

The previous example used a binary semaphore

- Counter initialized to 1
- Guarantees mutual exclusion of critical section by requiring wait/release operations to occur alternately

Cooperation Synchronization with Semaphores

Shared buffer example

- The buffer is implemented as an ADT with the operations **DEPOSIT** and **FETCH** as the methods to access the buffer
- Use two semaphores for cooperation: emptyspots and fullspots
- The semaphore counters are used to store the numbers of empty spots and full spots in the buffer

DEPOSIT

DEPOSIT must first check **emptyspots** to see if there is room in the buffer

If there is room, decrement emptyspots counter and insert the value

If there is no room, put the caller in **emptyspots** queue

When **DEPOSIT** is finished, it increments the **fullspots** counter

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FETCH

FETCH must first check fullspots to see if there is a value

If there is a full spot, decrement the fullspots counter and remove a value

If there are no values in the buffer, put the caller in the fullspots queue

When **FETCH** is finished, it increments the emptyspots counter

Example – Cooperation semaphore fullspots, emptyspots; task consumer; fullspots.count = 0; 100p emptyspots.count = BUFLEN;

task producer; loop -- produce value wait(emptyspots) DEPOSIT(value); release(fullspots)

end loop;

end producer;

wait(fullspots) FETCH(value); release(emptyspots) -- consume value

end loop; end consumer:

Competition Synchronization with Semaphores

fullspots and emptyspots are used for cooperation

- Make sure there is data for the consumer
- Make sure there is space for the producer

A binary semaphore, named access, is used to control access to the shared buffer

• Prevent the producer and consumer from using the same buffer location at the same time (competition synchronization)

Example - Cooperation/Competition

task producer;

loop -- produce value wait(emptyspots) wait(access) -- deposit value

wait(access)

release(access)

release(fullspots)

end loop;

end producer;

task consumer; 100p

wait(fullspots)

-- get value

release(access)

release(emptyspots) -- consume value

end loop;

end consumer;

Evaluation of Semaphores

Misuse of semaphores can cause failures in

- 1. Cooperation synchronization e.g., the buffer will overflow if the wait of fullspots is left out
- 2. Competition synchronization e.g., The program will deadlock if the release of access is left out

Per Brinch Hansen (1973)

" The semaphore is an elegant synchronization tool for an ideal programmer who never makes mistakes'

Monitors

Introduced by Brinch Hansen in 1973 Abstract Data Type for shared data The idea: encapsulate the shared data and its

operations to restrict access Instances are statically created by declarations

Hybrid implementations in Ada, Java, C#



Monitors - Competition

A monitor allows only one process at a time to execute the monitor's subprograms

Calls are queued if the monitor is busy at the time of call

Shared data and access methods reside in the monitor, not in the client program Mutually exclusive access to shared data is built in



Shared Buffer with Monitors

procedure entry - only one can be executing at any given time delay - places process that calls it in the specified queue and removes its exclusive access rights to the monitor continue - disconnect process that calls it from the monitor and check specified queue for processes suspended by a delay operation

Shared Buffer with Monitors Initialization code for databuf: begin filled := 0; next_in := 1; next_out := 1; end;



type producer = process(databuf:db) cycl e -- produce value nv

buffer.deposit(nv) end; end producer; type consumer =
 process(databuf : db)
 cycl e
 buffer.fetch(sv)
 -- consume value sv
 end;
end consumer:

Shared Buffer with Monitors

Program that uses shared buffer:

var a_producer : producer; a_consumer : consumer; a_buffer : databuf;

begi n

init
 a_buffer, a_producer(a_buffer),
 a_consumer(a_buffer);
end;

Evaluation of Monitors

The monitor ADT avoids competition synchronization problems that can occur with semaphores Co-operation has the same problems as semaphores Java threads are based on the idea of monitors