

CSIS 3103
Graphs

Graphs

Tree nodes have only one parent
 Graphs do not have this limitation
 Graphs algorithms are used in

- large communication networks
- software that makes the Internet function

Graphs describe

- roads maps
- airline routes
- course prerequisites

Graph Terminology

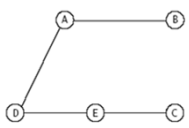
Graph: A data structure that consists of a set of *vertices* (nodes) and a set of *edges* (relations)

- Edges represent paths or connections between the vertices
- The set of vertices and the set of edges must both be finite

Visual Representation of Graphs

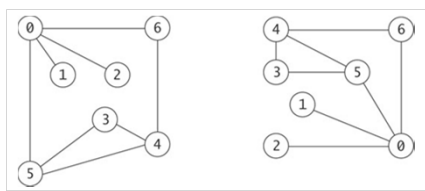
Vertices: points or labeled circles
 Edges: lines joining the vertices

$V = \{A, B, C, D, E\}$
 $E = \{\{A, B\}, \{A, D\}, \{C, E\}, \{D, E\}\}$



Visual Representation of Graphs

The layout of the vertices and the labeling are not relevant



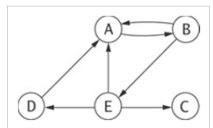
$V = \{0, 1, 2, 3, 4, 5, 6\}$
 $E = \{\{0, 1\}, \{0, 2\}, \{0, 5\}, \{0, 6\}, \{3, 5\}, \{3, 4\}, \{4, 5\}, \{4, 6\}\}$

Directed and Undirected Graphs

Undirected graph: The edges have no direction

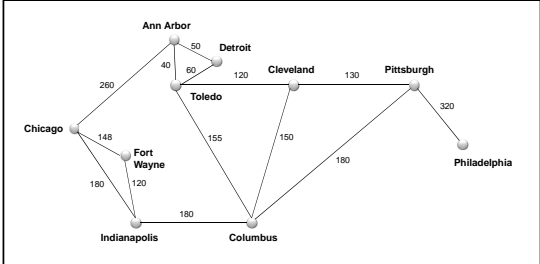
Directed graph (digraph): Each edge is directed from one vertex to another (or the same) vertex

$\{\{A, B\}, \{B, A\}, \{B, E\}, \{D, A\}, \{E, A\}, \{E, C\}, \{E, D\}\}$



Weighted Graphs

A graph in which each edge carries a value



More Terminology

Adjacent vertices: Two vertices in a graph that are connected by an edge

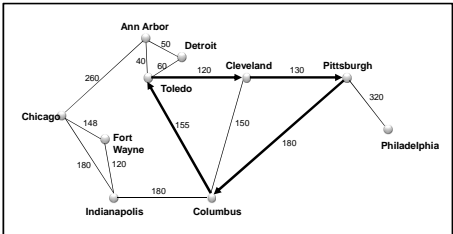
Path: A sequence of vertices where each successive vertex is adjacent to its predecessor

Cycle: A path from a node back to itself

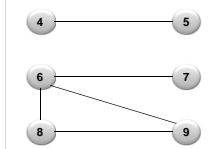
Acyclic graph: A graph with no cycles

Connected graph: A graph in which every vertex is reachable from every other vertex

Cycle Connected graph

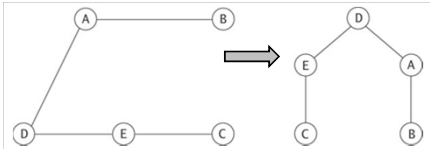


Unconnected graph



Graphs and Trees

A tree is a special case of a graph
 Any graph that is
 connected
 contains no cycles
 can be viewed as a tree by making one of the vertices the root



The Graph ADT

A graph ADT needs to support

- Creating a graph with a specified number of vertices
- Iterating through all of the vertices in the graph
- Iterating through the vertices that are adjacent to a specified vertex
- Determining whether an edge exists between two vertices
- Finding the weight of an edge between two vertices
- Inserting an edge into the graph

The Java API does not provide a Graph ADT

The Edge Class (for weighted digraphs)

Data Field	Attribute
<code>private int dest</code>	The destination vertex for an edge.
<code>private int source</code>	The source vertex for an edge.
<code>private double weight</code>	The weight.
Constructor	
<code>public Edge(int source, int dest)</code>	Constructs an Edge from source to dest. Sets the weight to 1.0.
<code>public Edge(int source, int dest, double w)</code>	Constructs an Edge from source to dest. Sets the weight to w.
Method	
<code>public boolean equals(Object o)</code>	Compares two edges for equality. Edges are equal if their source and destination vertices are the same. The weight is not considered.
<code>public int getDest()</code>	Returns the destination vertex.
<code>public int getSource()</code>	Returns the source vertex.
<code>public double getWeight()</code>	Returns the weight.
<code>public int hashCode()</code>	Returns the hash code for an edge. The hash code depends only on the source and destination.
<code>public String toString()</code>	Returns a string representation of the edge.

Implementing the Graph ADT

The most common representations of graphs:

Adjacency lists: Edges are represented by an array of lists where each list stores the vertices adjacent to a particular vertex

Adjacency matrix: Edges are represented by a two dimensional array

Adjacency List

Adjacency List

Adjacency Matrix

(Unweighted graph entries can be boolean values)

The Graph Class Hierarchy

Class AbstractGraph

Data Field	Attribute
private boolean directed	true if this is a directed graph.
private int numV	The number of vertices.
Constructor	Purpose
public AbstractGraph(int numV, boolean directed)	Constructs an empty graph with the specified number of vertices and with the specified directed flag. If directed is true, this is a directed graph.
Method	Behavior
public int getNumV()	Gets the number of vertices.
public boolean isDirected()	Returns true if the graph is a directed graph.
public void loadEdgesFromFile(Scanner scan)	Loads edges from a data file.
public static Graph createGraph(Scanner scan, boolean isDirected, String type)	Factory method to create a graph and load the data from an input file.

The ListGraph Class

Data Field	Attribute
private List<Edge>[] edges	An array of Lists to contain the edges that originate with each vertex.
Constructor	Purpose
public ListGraph(int numV, boolean directed)	Constructs a graph with the specified number of vertices and directionality.
Method	Behavior
public Iterator<Edge> edgeIterator(int source)	Returns an iterator to the edges that originate from a given vertex.
public Edge getEdge(int source, int dest)	Gets the edge between two vertices.
public void insert(Edge e)	Inserts a new edge into the graph.
public boolean isEdge(int source, int dest)	Determines whether an edge exists from vertex source to dest.

Graph Traversals

- Most graph algorithms involve visiting each vertex in a systematic order
- The most common traversal algorithms
 - Breadth first search
 - Depth first search

Breadth-First Search

Start at a vertex and visit it, then visit all vertices that are adjacent to it, then visit vertices with path length 2 from it, path length 3, etc.

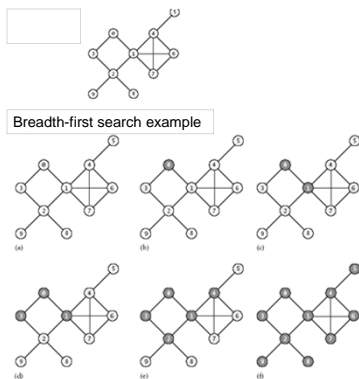
- Must visit all nodes for which the shortest path from the start node is length k before visiting any node for which the shortest path from the start node is length $k + 1$

Algorithm for Breadth-First Search

Algorithm for Breadth-First Search

1. Take an arbitrary start vertex, mark it identified (color it light blue), and place it in a queue.
2. **while** the queue is not empty
3. Take a vertex, u , out of the queue and visit u .
4. **for** all vertices, v , adjacent to this vertex, u
5. **if** v has not been identified or visited
6. Mark it identified (color it light blue).
7. Insert vertex v into the queue.
8. We are now finished visiting u (color it dark blue).

Breadth-First Search



Breadth-First Search

Trace of Breadth-First Search of Graph in Figure 12.15

Vertex Being Visited	Queue Contents After Visit	Visit Sequence
0	1 3	0
1	3 2 4 6 7	0 1
3	2 4 6 7	0 1 3
2	4 6 7 8 9	0 1 3 2
4	6 7 8 9 5	0 1 3 2 4
6	7 8 9 5	0 1 3 2 4 6
7	8 9 5	0 1 3 2 4 6 7
8	9 5	0 1 3 2 4 6 7 8
9	5	0 1 3 2 4 6 7 8 9
5	empty	0 1 3 2 4 6 7 8 9 5

Depth-First Search

Start at a vertex and visit it,
 choose one adjacent vertex to visit,
 then choose a vertex adjacent to that vertex...,
 ...and so on until you can go no further;
 then back up and see whether a new vertex
 can

FIGURE 12.18
 Graph to Be Traversed
 Depth First



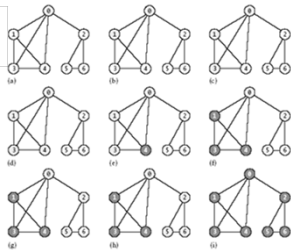
Algorithm for Depth-First Search

Algorithm for Depth-First Search

1. Mark the current vertex, u , visited (color it light blue), and enter it in the discovery order list
2. for each vertex, v , adjacent to the current vertex, u
3. if v has not been visited
4. Set parent of v to u .
5. Recursively apply this algorithm starting at v .
6. Mark u finished (color it dark blue) and enter u into the finish order list.

Depth-First Search

Depth-first
 search
 example



Depth-First Search
 Trace of Figure 12.18



Depth-First Search

Trace of Depth-First Search of Figure 12.19

Operation	Adjacent Vertices	Discovery (Visit) Order	Finish Order
Visit 0	1, 2, 3, 4	0	
Visit 1	0, 3, 4	0, 1	
Visit 3	0, 1, 4	0, 1, 3	
Visit 4	0, 1, 3	0, 1, 3, 4	
Finish 4			4
Finish 3			4, 3
Finish 1			4, 3, 1
Visit 2	0, 5, 6	0, 1, 3, 4, 2	
Visit 5	2, 6	0, 1, 3, 4, 2, 5	
Visit 6	2, 5	0, 1, 3, 4, 2, 5, 6	
Finish 6			4, 3, 1, 6
Finish 5			4, 3, 1, 6, 5
Finish 2			4, 3, 1, 6, 5, 2
Finish 0			4, 3, 1, 6, 5, 2, 0